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This section should be covered relatively rapidly to get quickly to the actual solution methods in the next sections. Equations (1)–(3) are just examples, not for solution, but the student will see that solutions of (1) and (2) can be found by calculus, and a solution $y = e^x$ of (3) by inspection. Problem Set 1.1 will help the student with the ...

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Prof. Jensen for substantially helping in preparing the exercises to Chap. 7. The author further acknowledges assistance from Carl de Boer in preparing the notes to Chap. 2 and to Werner C. Rheinboldt for helping with the notes to Chap. 4. Last but not least, he owes a measure of gratitude to Connie Wilson for typing a preliminary

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mend that the reader write out her/his own solution to the Example before reading the solution in the text. Some introductory Mechanics courses are advertised as not requiring any knowledge of calculus, but calculus usually sneaks in even if anonymously (e.g. in the derivation of the acceleration of a particle moving in a circle

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$7.5 \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} 2 \\ 6 \\ 4 \end{bmatrix} + 2 \begin{bmatrix} 5 \\ 7 \\ 3 \end{bmatrix} + 7 \begin{bmatrix} 3 \\ 7 \\ 5 \end{bmatrix}$ means $c + d = 2$ $2c + 3d = 5$ $3c + 4d = 7$: I leave the solution to you. The vector $b = (2;5;7)$ does lie in the plane of v and w . If the 7 changes to any other number, then b won't lie in the plane—it will not be a combination of v and w , and the three equations will have no solution. Now I can describe the first part ...

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